1.	Name of Course					Control Theory						
2.	Course Code					JCOT7313						
		the fi	rst digi	t identi	ify leve	ubject is offered., JCOT = the remaining three alphabet identify the el of study; in this case undergraduate level, 731 3= the second and dentify credit value or credit hours						
3.												
4.	Rationale for the inclusion of the	cours	e/mod	lule in	the	Knowledge of control theory is essential in electrical and						
	programme				electronics engineering. Moreover, acquiring knowledge control theory enable engineer to design feedback control systems.							
5.	Semester and Year offered				Year 3, Semester 2							
6.	Total Student Learning Time (SLT)	Face to Face			9	Total Guided and Independent Learning						
	L = Lecture T = Tutorial P = Practical IS= Independent Study	L 42	T 7	P	IS 65	Total Guided and Independent Learning = 120						
7.	Credit Value	I	ı		1	3.0						
	Lecture: 3 hours per week x 14 weeks Tutorial: 1 hour per week x 7 weeks Practical: 2 hours x 3weeks											
8.	Prerequisite (if any)				JSSY1043: Signal and System JMAT1023: Engineering Mathematic II							
9.	Course Objectives 1. To introduce the control theo 2. To equip the students with the	•	wledg	e feed	lback	control system.						

Course Learning Outcomes (CLO)

At the end of the semester students should be able to:

- CLO1: To understand the basic application of feedback control system;
- CLO2: To construct a mathematical model of a dynamic system that includes a control system;
- CLO3: To Simplify mathematical models to linear, time-invariant systems through linearization and block diagram reduction.

10. Transferable Skills:

This course is expected the development of the following transferable skills:

- An ability to manage time and task
- An ability to learn both independently and co—operatively;
- An ability to take responsibility and carry out laboratory test;
- An ability to take initiative and lead other;
- An ability to use software where relevant to the subject.

11. Teaching-learning and assessment strategy

A variety of learning strategies are used throughout the course, including the following

- Classroom Lesson; Lecturer and power point presentation
- Tutorial session
- Student- lecturer Discussion

	Collaborative and co-collaborative and co-coll	perative learn;	;	
	 Independent study. 			
	Assessment:			
	Course works		40%	
	Assignment	5%		
	Tutorial	5%		
	Quizzes	5%		
	Laboratory works	10%		
	Test	15%		
	Final Examination		60%	
	<u>Total</u>	<u>;</u>	<u> 100%</u>	
12.	Synopsis:			
	This course is very important of	ourse in the fie	eld of electri	cal engineering. The objective of course is to introduce students

This course is very important course in the field of electrical engineering. The objective of course is to introduce students to the techniques of analysis and design of feedback control systems based mainly on classical theory.

13. Mode of Delivery:

Lectures;

Tutorials;

Laboratory works

CLO-PLO	Assessment Tool	1	2	3	4	5
Marks		0-39	40-49	50-59	60-74	75-10
Grade		(F)	(D,D+)	(C-,C,C+)	(B-,B,B+)	(A-,A,A
CLO1: To understand the basic application of feedback control system;	Assignment Tutorials Lab works Quizzes Test Examination	Fail To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out laboratory test	Poor To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out laboratory test	Satisfactory To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out laboratory test	Good To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out laboratory test	excellent To - manage tir and task - learn both independe and cooperativ - take responsibil and carry of laboratory
To Construct a mathematical model of a dynamic system that includes a control system;	Assignment Tutorials Construct a Lab works thematical model of a lamic system that Test Assignment Tutorials Lab works Quizzes In Test		Poor To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out laboratory test	Satisfactory To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out laboratory test	Good To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out laboratory test	Excellent To - manage tir and task - learn both independe and cooperativ - take responsibil and carry of laboratory
CLO3: To Simplify mathematical models to linear, time-invariant systems through linearization and block diagram reduction;	Assignment Tutorials Lab works Quizzes Test Examination	Fail To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out	Poor To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out	Satisfactory To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out	Good To: - manage time and task - learn both independently and cooperatively - take responsibility and carry out	excellent To - manage tir and task - learn both independe and cooperativ - take responsibil and carry of

15.	5. Mapping of the Programme Objectives to the Programme Learning Outcomes											
	Programme Learning Outcomes (PO) Programme Objectives (PO)	PLO1: Ability to acquire and apply knowledge of science and engineering fundamentals.	PLO2: Acquired in-depth technical competence in electrical engineering discipline.	PLO3: Ability to undertake problem identification, formulation and solution;	PLO4: Ability to utilise systems approach to design and evaluate operational performance.	PLO5: Understanding of the principles of design for sustainable development;	PLO6: Understanding of professional and ethical responsibilities and commitment to them.	PLO7: Ability to communicate effectively, not only with engineers but also with the community at large.	PLO8: Ability to function effectively as an individual and in a group with the capacity to be a leader or manager;	PLO9: Understanding of the social, cultural, global and environmental responsibilities of a professional engineer	PLO10: Recognising the need to undertake lifelong learning, and possessing/acquiring the capacity to do so	PLO11: Ability become entrepreneur
	PO1: To produce graduates with excellent knowledge and competency in Electrical and Electronic Engineering;	✓					1		✓ ×		- - · ·	
	PO2: To produce graduates with professional, generic attributes to meet the present and future global demands.											
	PO3: To produce graduates with Islamic humanistic values and reinvention skills to meet the requirement of a dynamic environment. These skills include Civil Intelligence, Moral Intelligence, Self-Reliance and Communication Skills.											

16. Mapping of the course I	11 0											
Course Learning Outcome (CLO) CLO1:	PLO1: Ability to acquire and apply knowledge of science and engineering fundamentals.	PLO2: Acquired in-depth technical competence in electrical engineering discipline.	PLO3: Ability to undertake problem identification, formulation and solution;	PLO4: Ability to utilise systems approach to design and evaluate operational performance.	PLO5: Understanding of the principles of design for sustainable development;	PLO6: Understanding of professional and ethical responsibilities and commitment to them.	PLO7: Ability to communicate effectively, not only with engineers but also with the community at large.	PLO8: Ability to function effectively as an individual and in a group with the capacity to be a leader or manager;	PLO9: Understanding of the social, cultural, global and environmental responsibilities of a professional engineer	PLO10: Recognising the need to undertake lifelong learning, and possessing/acquiring the capacity to do so	PLO11: Ability become entrepreneur	
To understand the basic application of feedback control system;	✓							√		✓		
CLO2: To Construct a mathematical model of a dynamic system that includes a control system;	✓							√		√		
CLO3: To Simplify mathematical models to linear, time-invariant systems through linearization and block diagram reduction;	✓							✓		√		

17.	Conte	ent outline of the course/module and the SLT per topic					
					SLT (Hour)	
	Detai	IS	L	Т	Р	IS	Total
	Topic 1	 Introduction and basic mathematics. An introduction to control systems, Types and effects of feedback. Complex variables, difference and differential equations and Laplace transform. 	3	-	-	8	11
	Topic 2	Transfer Function, Block Diagrams and Signal-Flow Graphs. • Impulse response, • transfer functions, • block diagram, signal-flow graph and gain formula	3	1	-	10	14
	Topic 3	Mathematical Modelling for Physical Systems. • Electrical networks, • Mechanical systems, • Sensors and encoders, • Non-linear systems. Linear System Stability. • Bounded-input bounded-output, • Zero-input stability, • Routh-Hurwitz • Stability criterion.	9	2	-	15	26
	Topic 4	Time Response Analysis. Time response, Test signals, Time-domain specifications, Steady-state error, Transient response of second-order systems, Effects of zero-pole placements, Higher-order system approximation. Root Locus Techniques. Root locus characteristics, building root locus and root contour	9	1	-	10	20
	Topic 5	Frequency Response Analysis Bode diagram, Polar plot, Nichols plot. Nyquist stability criterion Non-mathematical description of Nyquist criterion, Interpretation of stability. Relative stability Gain and phase margins. Closed-loop frequency response analysis M and N contours, Nichols chart.	9	1	-	10	20

		Time-d	omain and Frequency-domain Controller Design.					
		•	Phase-lead controller,					
		•	Phase-lag controller,					
		•	Lead-lag controller,					
		•	Zero-pole cancellation,					
	9	•	Lad and feed forward compensation)	9	2	_	12	
	Topic	Compe	nsation Techniques					23
	2	•	Compensation techniques lag,					
		•	Lead and lag-lead compensation,					
		•	PD,					
		•	PI and PID controllers					
		•	Cascade compensation based on root locus method.					
			Introduction to feedback compensation					
	_							
	1 22	1.	PID controller design.					
	Practical	2.	Frequency response analysis	-	-	6	-	6
	P							
		<u> </u>						
			Total SLT (Hour)	42	7	6	65	120
40			1	ı	1	l .	l .	

18. Main references supporting the course

1. Control Systems Engineering, 6th edition, 2008 (ISBN: 0471445770), Norman S. Nise, Wiley

Additional references supporting the course

- 1. Modern Control Engineering, 4th edition, 2008 (ISBN: 0130609072), K. Ogata, Prentice Hall
- 2. Modern Control Systems, 10th edition, 2005 (ISBN: 0-13-127765-0), R.C. Dorf & R.H. Bishop, Prentice Hall.
- 3. Automatic Control Systems, 8th edition, 2007(ISBN: 0471134767), B. C. Kuo, John Wiley & Sons

19. Other additional information

All materials will be available to the students in the library.